Closing Tue, Jan. 12: 12.1, 12.2, 12.3 Closing Thu, Jan. 14: 12.4(1), 12.4(2)

12.4 The Cross Product

We define the <u>cross product</u>, or <u>vector product</u>, for two 3-dimensional vectors,

$$a = \langle a_1, a_2, a_3 \rangle$$
 and $b = \langle b_1, b_2, b_3 \rangle$,
by $a x b = \begin{vmatrix} i & j & k \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} =$

 $(a_2b_3 - a_3b_2)\mathbf{i} - (a_1b_3 - a_3b_1)\mathbf{j} + (a_1b_2 - a_2b_1)\mathbf{k}$

Ex: If $\boldsymbol{a} = \langle 1,2,0 \rangle$ and $\boldsymbol{b} = \langle -1,3,2 \rangle$, then

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$$a x b = \begin{vmatrix} i & j & k \\ 1 & 2 & 0 \\ -1 & 3 & 2 \end{vmatrix} = -ji - (-j)i - (-j)j + (-j)k$$

12.5 Intro to Lines in 3D

In order to describe lines in 3D, we use parametric equations. Here is an example of 2D parametric lines:

- *Ex*: Consider the 2D line: y = 4x + 5.
 - (a) Find a vector that is parallel to the line. Call this vector **v**.
 - (b) Find a vector whose head
 touches the line when drawn
 from the origin.
 Call this vector r₀.
 - (c) We can reach all other points
 on the line by walking along r₀,
 then adding scale multiples of v.

This same idea works to describe any line in 2- or 3-dimensions.

The equation for a line in 3D: Find

 $v = \langle a, b, c \rangle =$ a vector parallel to the line.

 $r_0 = \langle x_0, y_0, z_0 \rangle =$ a position vector (*i.e.* (x_0, y_0, z_0)) is a point on the line)

Then all other points on the line can be obtained by

 $\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t \langle a, b, c \rangle$, which is sometimes written as:

$$r = r_0 + t v$$

